# Reduction of generalized complex structures 

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#### Abstract

We study reduction of generalized complex structures. More precisely, we investigate the following question. Let $J$ be a generalized complex structure on a manifold $M$, which admits an action of a Lie group $G$ preserving $J$. Assume that $M_{0}$ is a $G$-invariant smooth submanifold and the $G$-action on $M_{0}$ is proper and free so that $M_{G}:=M_{0} / G$ is a smooth manifold. Under what condition does $J$ descend to a generalized complex structure on $M_{G}$ ? We describe a sufficient condition for the reduction to hold, which includes the Marsden-Weinstein reduction of symplectic manifolds and the reduction of the complex structures in Kähler manifolds as special cases. As an application, we study reduction of generalized Kähler manifolds.


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## 1. Introduction

Generalized complex structures $[13,10]$ have been extensively studied recently due to their close connection with mirror symmetry. They include both symplectic and complex structures as extreme cases.

As is well known in symplectic geometry, a useful way of producing new symplectic manifolds is via the so called Marsden-Weinstein reduction [23]. This is a procedure for constructing symplectic manifolds from a Hamiltonian system with symmetry admitting a momentum map. Let us recall this construction briefly below. Suppose we are given a symplectic manifold $(M, \omega)$, an action of a Lie group $G$ on $M$ preserving the symplectic form, and an equivariant momentum map $\mu: M \rightarrow \mathfrak{g}^{*}$, i.e. $\mu$ satisfies the relations

$$
\mu(g \cdot x)=\operatorname{Ad}_{g^{-1}}^{*} \mu(x), \quad \forall g \in G, x \in M
$$

and

$$
\hat{A}\lrcorner \omega=d\langle\mu, A\rangle, \quad \forall A \in \mathfrak{g},
$$

where $\hat{A}$ denotes the fundamental vector field generated by $A \in \mathfrak{g}$. Assume that 0 is a regular value of the momentum map $\mu$ so that the preimage $M_{0}=\mu^{-1}(0)$ is a $G$-invariant smooth submanifold. Moreover, if we assume that the

[^0]$G$-action on $M_{0}$ is free and proper so that $M_{G}=M_{0} / G$ is a smooth manifold, then it inherits a natural symplectic structure [23] (see [27] for the symplectic reduction in the singular case). In the context of Poisson manifolds, a reduction procedure was carried out by Marsden and Ratiu [24] and Ortega and Ratiu for the singular case [25]. See [26] for a beautiful comprehensive study on Hamiltonian reductions.

On the other hand, since there is no such notion of momentum maps for complex manifolds, there does not exist a general scheme of reduction of $G$-invariant complex structures in the literature as far as we know. However, for a $G$-invariant Kähler manifold which admits an equivariant momentum map for the symplectic structure, one can prove that the complex structure can also descend to the symplectic reduced space $M_{G}=M_{0} / G$ so that $M_{G}$ becomes a Kähler manifold. This is the so called Kähler reduction.

There are several versions of Kähler reduction, which were due to Guillemin and Sternberg [11], Kirwan [16], and Hitchin et al. [12] respectively. A careful examination of the argument used by Guillemin and Sternberg in [11] shows that the following identity:

$$
\begin{equation*}
T_{x} M=T_{x} M_{0} \oplus j\left(T_{x}(G \cdot x)\right), \quad \forall x \in M_{0} \tag{1}
\end{equation*}
$$

plays an essential role in carrying out the reduction for the complex structure, where $j: T M \rightarrow T M$ is the complex structure of the Kähler manifold. Eq. (1) holds automatically when $M_{0}=\mu^{-1}(0)$ is the level set of the momentum map $\mu: M \rightarrow \mathfrak{g}^{*}$. Indeed this is exactly why the symplectic reduced space $M_{G}=M_{0} / G$ inherits a complex structure.

A natural question arises as to whether there is a reduction procedure for a $G$-invariant generalized complex structure which combines the above two special cases. More precisely, the question can be formulated as follows.

Let $J$ be a generalized complex structure on a manifold $M$, which admits an action of a Lie group $G$ preserving $J$. Assume that $M_{0}$ is a $G$-invariant smooth submanifold and the $G$-action on $M_{0}$ is free and proper so that $M_{G}:=M_{0} / G$ is a smooth manifold. Under what condition does $J$ descend to a generalized complex structure on $M_{G}$ ?

In this paper, we describe a sufficient condition for such a reduction. Our condition comprises many well-known examples as special cases including the above two important cases. In particular, even when $J$ is an honest complex structure, we derive some interesting condition for the reduction of the complex structure to hold, which seems to be new.

Below let us describe the main idea of our approach briefly. There are several equivalent definitions of generalized complex structures. A useful one for us is that a generalized complex structure on a manifold $M$ is a pair of transversal (complex) Dirac structures $\left(E_{+}, E_{-}\right)$on $M$ which are complex conjugate to each other. In other words $\left(E_{+}, E_{-}\right)$ constitutes a (complex) Lie bialgebroid in the sense of [20] (see [19]). Roughly, our approach is as follows. Using the inclusion map $M_{0} \rightarrow M$, one may pull back $E_{ \pm}$to $M_{0}$ to obtain a pair of complex conjugate Dirac structures on $M_{0}$. Since $J$ is $G$-invariant, using the push forward map $M_{0} \rightarrow M_{0} / G=M_{G}$, one obtains a pair of complex conjugate Dirac structures $E_{ \pm}^{\prime}$ on $M_{G}$. To ensure that this gives rise to a generalized complex structure on $M_{G}$, a necessary condition is that $E_{+}^{\prime} \cap E_{-}^{\prime}=0$. However, there is a subtlety. It is due to the difficulty that the pull back and push forward of Dirac structures may not be smooth bundles. This forces us to impose some extra smoothness assumptions. Indeed, in this paper we combine the pull back and push forward steps together to derive a sufficient condition for the reduction. Note that Dirac reduction in the real context was first studied by Blankenstein (see $[3,4]$ ) and by Blankenstein and Ratiu for the singular case [5] in connection with the study of Hamiltonian mechanics.

One may easily check that if one starts with a symplectic structure, the reduced generalized complex structure is still symplectic, while reduction of a complex structure is still a complex structure. Thus the two examples above are indeed special cases of our general condition. As an application, we study reduction of generalized Kähler manifolds, which generalizes the usual Kähler reduction [11,12,16]. Our paper only deals with the analogue of regular Kähler reduction. See [15] for the singular case.

The paper is organized as follows. In Section 2, we recall some basic materials in Dirac geometry. In particular, we describe the pull back and push forward constructions. In Section 3, we recall several equivalent definitions of generalized complex structures. Section 4 is devoted to the study of reduction of generalized complex structures. As corollaries, we consider several special examples including the reduction of usual complex structures, and the $B$ transform of symplectic structures. In Section 5, we give an explicit description of the reduced generalized complex structure in terms of the endomorphism $J_{G}$ of the vector bundle $T M_{G} \oplus T^{*} M_{G}$. In Section 6, as an application, we investigate the reduction of generalized Kähler structures.

As a special case when $G=\{*\}$, our main results would lead to conditions which guarantee submanifolds of a generalized complex manifold inheriting natural generalized complex structures. This topic was studied in detail separately by Barton and the first author [1]. Note though that the first investigation of the submanifolds of a generalized complex manifold was [2].

The results of this paper were announced at the conference "Poisson geometry" held in Trieste in July 2005, where we learned that Bursztyn, Cavalcanti and Gualtieri [6] were working on a related subject. Subsequently, we noticed that there have appeared several papers studying similar topics independently, including the one by Hu [14], the one by Lin and Tolman [21] and the one by Vaisman [29]. It would be interesting to clarify the relations between all these approaches.
Notation. We denote by $V_{\mathbb{C}}$ the complexified $V \otimes \mathbb{C}$ of a vector space $V$. Likewise, $T_{\mathbb{C}} M$ and $T_{\mathbb{C}}^{*} M$ respectively denote the tangent and cotangent bundles of a manifold $M$. If $W$ is a vector subspace of $V, W^{0}$ denotes the annihilator subspace of $W$ inside $V^{*}$. And if $V$ is endowed with an inner product, $W^{\perp}$ denotes the subspace of $V$ orthogonal to $W$. Finally, $\mathbf{i}$ denotes the imaginary number $\sqrt{-1}$.

## 2. Dirac geometry

In this section, we briefly review some basic ingredients of Dirac geometry which will be used in this paper. For details, see [7,8].

Given a vector space $V$, we consider the direct sum $V \oplus V^{*}$ endowed with the inner product

$$
\langle X+\xi, Y+\eta\rangle=\frac{1}{2}(\xi(Y)+\eta(X)), \quad \forall X, Y \in V, \xi, \eta \in V^{*} .
$$

We denote by $\rho$ and $\rho_{*}$ the natural projections of $V \oplus V^{*}$ onto $V$ and $V^{*}$ respectively. A Dirac structure on $V$ is a maximal isotropic subspace of $V \oplus V^{*}$ with respect to $\langle\cdot, \cdot\rangle$. The set of linear Dirac structures on $V$ is denoted by $\operatorname{Dir}(V)$.

Alternatively, a Dirac structure on a vector space can be described as follows. Let $L \in \operatorname{Dir}(V)$. Since $L$ is isotropic with respect to $\langle\cdot, \cdot\rangle$, there exists a natural skew-symmetric bilinear form $\Lambda$ on $L$ defined by

$$
\Lambda(X+\xi, Y+\eta)=\xi(Y)=-\eta(X), \quad \forall X+\xi, Y+\eta \in L .
$$

One easily checks that

$$
\Lambda\left(X+\xi_{1}, Y+\eta_{1}\right)=\Lambda\left(X+\xi_{2}, Y+\eta_{2}\right), \quad \forall X+\xi_{i}, Y+\eta_{i} \in L, i=1,2
$$

and

$$
\Lambda\left(X_{1}+\xi, Y_{1}+\eta\right)=\Lambda\left(X_{2}+\xi, Y_{2}+\eta\right), \quad \forall X_{i}+\xi, Y_{i}+\eta \in L, i=1,2 .
$$

Hence, there exists a 2 -form $\Omega$ on $\rho(L)$ and a 2-form $\pi$ on $\rho_{*}(L)$ defined, respectively, by

$$
\Omega(X, Y)=\Lambda(X+\xi, Y+\eta)=-\pi(\xi, \eta), \quad \forall X+\xi, Y+\eta \in L .
$$

Let $X \in \rho(L)$. Then there is a $\xi \in V^{*}$ such that $X+\xi \in L$. And we have $\Omega(X, Y)=\xi(Y), \forall Y \in \rho(L)$, or, equivalently, $X\lrcorner \Omega=\xi_{\mid \rho(L)}$, where $\xi_{\mid \rho(L)}$ denotes the restriction of $\xi \in V^{*}$ to $\rho(L)$. Thus

$$
X+\xi \in L \Longleftrightarrow\left\{\begin{array}{l}
X \in \rho(L) \\
X\lrcorner \Omega=\xi_{\mid \rho(L)} .
\end{array}\right.
$$

Thus knowing the Dirac structure $L$ on $V$ is exactly the same as knowing the subspace $\rho(L)$ of $V$ and the 2-form $\Omega$ on $\rho(L)$. Similarly, $L$ is equivalent to the pair $\left(\rho_{*}(L), \pi\right)$.

Therefore, we have the converse: any subspace $R \subset V$ endowed with a 2-form $\Omega$ defines a Dirac structure

$$
\left.\left\{X+\xi \mid X \in R, \xi \in V^{*}, X\right\lrcorner \Omega=\xi \mid R\right\}
$$

on $V$ and any subspace $R^{*} \subset V^{*}$ endowed with a 2-form $\pi$ defines a Dirac structure

$$
\left\{X+\xi \mid \xi \in R^{*}, X \in V, \pi(\xi, \eta)=-\eta(X), \forall \eta \in R^{*}\right\}
$$

on $V$.

Dirac structures can be pulled back and pushed forward using a linear map. Let $V \xrightarrow{\phi} W$ be a linear map. Consider a Dirac structure $L_{W}$ on $W$ and its associated pair ( $\rho\left(L_{W}\right), \Omega_{L_{W}}$ ). The 2 -form $\Omega_{L_{W}}$ pulls back to the preimage $\phi^{-1}\left(\rho\left(L_{W}\right)\right)$, yielding the pair $\left(\phi^{-1}\left(\rho\left(L_{W}\right)\right), \phi^{*} \Omega_{L_{W}}\right)$. The Dirac structure on $V$ associated with this new pair is called the backward image of $L_{W}$ through $\phi$ and is denoted by $\mathcal{B} \phi\left(L_{W}\right)$.

Let $W^{*} \xrightarrow{\phi^{*}} V^{*}$ be the dual of $\phi$. Consider a Dirac structure $L_{V}$ on $V$ and its associated pair $\left(\rho_{*}\left(L_{V}\right), \pi_{L_{V}}\right)$. The pullback of the 2-form $\pi_{L_{V}}$ to the preimage $\left(\phi^{*}\right)^{-1}\left(\rho_{*}\left(L_{V}\right)\right)$ is equal to $\phi \pi_{L_{V}}$. The Dirac structure on $W$ associated with the pair $\left(\left(\phi^{*}\right)^{-1}\left(\rho_{*}\left(L_{V}\right)\right), \phi \pi_{L_{V}}\right)$ is called the forward image of $L_{V}$ through $\phi$ and is denoted by $\mathcal{F} \phi\left(L_{V}\right)$.

One easily checks that

$$
\mathcal{B} \phi\left(L_{W}\right)=\left\{X+\phi^{*} \xi \mid X \in V, \xi \in W^{*}, \phi X+\xi \in L_{W}\right\}
$$

and

$$
\mathcal{F} \phi\left(L_{V}\right)=\left\{\phi(X)+\xi \mid X \in V, \xi \in W^{*}, X+\phi^{*} \xi \in L_{V}\right\} .
$$

Let $M$ be a smooth manifold. A Dirac structure on $M$ is a smooth subbundle $L \subset T M \oplus T^{*} M$ which determines a Dirac structure in $T_{m} M \oplus T_{m}^{*} M$ for each $m \in M$ and whose space of sections is closed under the (skew-symmetric) Courant bracket on $\Gamma\left(T M \oplus T^{*} M\right)$ defined by

$$
[X+\xi, Y+\eta]=[X, Y]+\mathcal{L}_{X} \eta-\mathcal{L}_{Y} \xi+\frac{1}{2} d(\xi(Y)-\eta(X)), \quad \forall X, Y \in \mathfrak{X}(M), \xi, \eta \in \Omega^{1}(M)
$$

In general, the Courant bracket does not satisfy the Jacobi identity. However, it does when restricted to the space $\Gamma(L)$ of sections of a Dirac subbundle $L \subset T M \oplus T^{*} M$. Then $L \rightarrow M$ inherits a Lie algebroid structure with the projection $L \xrightarrow{\rho_{L L}} T M$ as anchor map and the restriction of the Courant bracket as Lie algebroid bracket [8].

Although the backward and forward images of a Dirac structure through the differential of a smooth map are always pointwise Dirac structures, they are generally not constant rank smooth vector bundles. The remainder of this section is devoted to the description of situations in which backward and forward images of Dirac structures are again Dirac structures.

Definition 2.1. Let $M \xrightarrow{\varphi} N$ be a smooth map. Two generalized tangent vectors $X+\xi \in T M \oplus T^{*} M$ and $Y+\eta \in T N \oplus T^{*} N$ are said to be $\varphi$-related, denoted by $X+\xi \stackrel{\varphi}{\rightsquigarrow} Y+\eta$, if $\varphi_{*} X=Y$ and $\varphi^{*} \eta=\xi$. Clearly, this notion extends to sections.

Lemma 2.2. Assume that $\sigma_{M}^{i} \in \Gamma\left(T M \oplus T^{*} M\right)$ and $\sigma_{N}^{i} \in \Gamma\left(T N \oplus T^{*} N\right)$ satisfy $\sigma_{M}^{i} \underset{\sim}{\varphi} \underset{N}{i}$, where $i=1$, 2. Then

$$
\left[\sigma_{M}^{1}, \sigma_{M}^{2}\right] \stackrel{\varphi}{\sim}\left[\sigma_{N}^{1}, \sigma_{N}^{2}\right],
$$

where the bracket on the LHS refers to the Courant bracket on $\Gamma\left(T M \oplus T^{*} M\right)$ while the bracket on the RHS refers to the Courant bracket on $\Gamma\left(T N \oplus T^{*} N\right)$.

Proof. Write $\sigma_{M}^{i}=X^{i}+\xi^{i}$ and $\sigma_{N}^{i}=Y^{i}+\eta^{i}$, where $X^{i} \in \mathfrak{X}(M), \xi^{i} \in \Omega^{1}(M), Y^{i} \in \mathfrak{X}(N)$ and $\eta^{i} \in \Omega^{1}(N)$ for $i=1,2$. Since $\sigma_{M}^{i}$ and $\sigma_{N}^{i}$ are $\varphi$-related, $\varphi_{*} X^{i}=Y^{i}$ and $\varphi^{*} \eta^{i}=\xi^{i}$ for $i=1$, 2. Then

$$
\left[\sigma_{M}^{1}, \sigma_{M}^{2}\right]=\left[X^{1}, X^{2}\right]+\mathcal{L}_{X^{1}} \xi^{2}-\mathcal{L}_{X^{2}} \xi^{1}+\frac{1}{2} d\left(\xi^{1}\left(X^{2}\right)-\xi^{2}\left(X^{1}\right)\right)
$$

and

$$
\left[\sigma_{N}^{1}, \sigma_{N}^{2}\right]=\left[Y^{1}, Y^{2}\right]+\mathcal{L}_{Y^{1}} \eta^{2}-\mathcal{L}_{Y^{2}} \eta^{1}+\frac{1}{2} d\left(\eta^{1}\left(Y^{2}\right)-\eta^{2}\left(Y^{1}\right)\right)
$$

Now

$$
\varphi_{*}\left[X^{1}, X^{2}\right]=\left[\varphi_{*} X^{1}, \varphi_{*} X^{2}\right]=\left[Y^{1}, Y^{2}\right],
$$

and

$$
\begin{aligned}
\varphi^{*}\left(\mathcal{L}_{Y^{1}} \eta^{2}\right) & =\varphi^{*}\left(i_{Y^{1}} d \eta^{2}+d i_{Y^{1}} \eta^{2}\right) \\
& =\varphi^{*} i_{\varphi_{*} X^{1}} d \eta^{2}+\varphi^{*} d\left(\eta^{2}\left(Y^{1}\right)\right) \\
& =i_{X^{1}} \varphi^{*} d \eta^{2}+d\left(\xi^{2}\left(X^{1}\right)\right) \\
& =i_{X^{1}} d \xi^{2}+d i_{X^{1}} \xi^{2} \\
& =\mathcal{L}_{X^{1}} \xi^{2}
\end{aligned}
$$

Similarly, we have

$$
\varphi^{*}\left(\mathcal{L}_{Y^{2}} \eta^{1}\right)=\mathcal{L}_{X^{2}} \xi^{1}
$$

Finally

$$
\varphi^{*} d\left(\eta^{1}\left(Y^{2}\right)-\eta^{2}\left(Y^{1}\right)\right)=d\left(\xi^{1}\left(X^{2}\right)-\xi^{2}\left(X^{1}\right)\right)
$$

since

$$
\varphi^{*}\left(\eta^{1}\left(Y^{2}\right)\right)=\varphi^{*}\left(\eta^{1}\left(\varphi_{*} X^{2}\right)\right)=\left(\varphi^{*} \eta^{1}\right)\left(X^{2}\right)=\xi^{1}\left(X^{2}\right)
$$

This concludes the proof.
Recall that a generalized smooth subbundle of a vector bundle $E \rightarrow M$ is a subbundle $V \subset E$ (whose fibers may not be of constant ranks) such that for any vector $v \in V_{m}$ there is a local smooth section $s$ of $V$ extending $v$, i.e. $\left.s\right|_{m}=v$.

Proposition 2.3. (1) Let $M \xrightarrow{i} N$ be an embedding and $L_{N}$ a Dirac structure on $N$. If, for any vector $v_{m} \in$ $\mathcal{B} i\left(L_{N}\right)$, there exists a local smooth section $s$ of $L_{N}$ defined in a neighborhood of $i(m) \in N$, such that $s_{\mid M} \in \Gamma_{\mathrm{loc}}\left(\left.i_{*} T M \oplus T^{*} N\right|_{M}\right)$ and $\left.v_{m} \stackrel{i}{\rightsquigarrow} s\right|_{i(m)}$, then $\mathcal{B} \phi\left(L_{N}\right)$ is a Dirac structure on $M$. In particular, the above condition holds if $\left.L_{N}\right|_{M} \cap\left(\left.i_{*}(T M) \oplus T^{*} N\right|_{M}\right)$ is a generalized smooth subbundle.
(2) Let $M$ be a smooth manifold endowed with a proper and free action of a Lie group $G$. Let $\pi$ denote the canonical projection of $M$ onto $N:=M / G$. If $L_{M}$ is a $G$-invariant Dirac structure on $M$, and for any vector $v_{n} \in \mathcal{F} \pi\left(L_{M}\right)$, there exists a local smooth section $s$ of $L_{M}$ defined in a neighborhood of a point $m \in M$ in the fiber of $\pi$ over $n$ such that $s \in \Gamma_{\mathrm{loc}}\left(T M \oplus \pi^{*}\left(T^{*} N\right)\right)$ and $\left.s\right|_{m} \stackrel{\pi}{\rightsquigarrow} v_{n}$, for instance when $L_{M} \cap\left(T M \oplus \pi^{*}\left(T^{*} N\right)\right)$ is a generalized smooth subbundle, then $\mathcal{F}_{\pi}\left(L_{M}\right)$ is a Dirac structure on $N$.

Proof. (1). First, we observe that $\mathcal{B i}\left(L_{N}\right)$ is well defined since $i$ is injective. The assumption implies that any vector $v_{m} \in \mathcal{B} i\left(L_{N}\right)$ admits a local section $\tilde{s}$ of $\mathcal{B} i\left(L_{N}\right)$ such that $\tilde{s} \rightsquigarrow s$, where $s$ is a local smooth section of $L_{N}$ defined in a neighborhood of $i(m) \in N$ such that $s_{\mid M} \in \Gamma_{\mathrm{loc}}\left(\left.i_{*} T M \oplus T^{*} N\right|_{M}\right)$. Then $\tilde{s}$ must be a smooth local section. Therefore $\mathcal{B i}\left(L_{N}\right)$ is a smooth subbundle.

Now for any point $m \in M$, take a basis $\left\{\left.v^{k} \in \mathcal{B} i\left(L_{N}\right)\right|_{m}\right\}_{k \in K}$. Let $\tilde{s}^{k}$ be a local section of $\mathcal{B} i\left(L_{N}\right)$ through $v^{k}$ as above. Then $\tilde{s}^{k} \stackrel{i}{\rightsquigarrow} s^{k}$, where $s^{k}$ is a local smooth section of $L_{N}$. Thus $\left[\tilde{s}^{k}, \tilde{s}^{l}\right], \forall k, l$, is still a local smooth section of $\mathcal{B} i\left(L_{N}\right)$ according to Lemma 2.2. Hence it follows that $\mathcal{B i}\left(L_{N}\right)$ is Courant involutive.

For the second part, note that any element $v_{m} \in \mathcal{B} i\left(L_{N}\right)$ naturally induces an element $\left.v_{i(m)} \in L_{N}\right|_{M} \cap$ $\left(\left.i_{*}(T M) \oplus T^{*} N\right|_{M}\right)$ such that $v_{m} \stackrel{i}{\rightsquigarrow} v_{i(m)}$. Thus the condition is satisfied since $\left.L_{N}\right|_{M} \cap\left(\left.i_{*}(T M) \oplus T^{*} N\right|_{M}\right)$ is a generalized smooth subbundle by assumption.
(2). First, we observe that $\mathcal{F} \pi\left(L_{M}\right)$ is well defined since $L_{M}$ is $G$-invariant. Now for any vector $v_{n} \in \mathcal{F} \pi\left(L_{M}\right)$, let $s$ be a local section of $L_{M}$ defined in a neighborhood of a point $m \in \pi^{-1}(n)$ such that $s \in \Gamma_{\text {loc }}\left(T M \oplus \pi^{*}\left(T^{*} N\right)\right)$ and $\left.s\right|_{m} \stackrel{\pi}{\sim} v_{n}$. Let $L \subset M$ be a slice through $m$ transversal to the $G$-orbits. Since $L_{M}$ is $G$-invariant, there is a local smooth section $\hat{s}$ of $L_{M}$ such that $\left.\hat{s}\right|_{L}=\left.s\right|_{L}$. It is clear that $\hat{s} \in \Gamma_{\text {loc }}\left(T M \oplus \pi^{*}\left(T^{*} N\right)\right)$. Hence it induces a local section $\tilde{s}$ of $\mathcal{F} \pi\left(L_{M}\right)$ through $v_{n}$. Therefore $\mathcal{F} \pi\left(L_{M}\right)$ is indeed a smooth subbundle. The rest can be proved like in (1).

## 3. Generalized complex structures

Let $V$ be a vector space. Consider a linear endomorphism $J$ of $V \oplus V^{*}$ such that $J^{2}=-I$ and $J$ is orthogonal with respect to the inner product

$$
\langle X+\xi, Y+\eta\rangle=\frac{1}{2}(\xi(Y)+\eta(X)), \quad \forall X, Y \in V, \xi, \eta \in V^{*} .
$$

Such a linear map is called a linear generalized complex structure by Hitchin and Gualtieri [10,13]. The complexified vector space $\left(V \oplus V^{*}\right) \otimes \mathbb{C}$ decomposes as the direct sum

$$
\left(V \oplus V^{*}\right) \otimes \mathbb{C}=E_{+} \oplus E_{-}
$$

of the eigenbundles of $J$ corresponding to the eigenvalues $\pm \mathbf{i}$ respectively, i.e.,

$$
E_{ \pm}=\left\{(X+\xi) \mp \mathbf{i} J(X+\xi) \mid X+\xi \in V \oplus V^{*}\right\} .
$$

Both eigenspaces are maximal isotropic with respect to $\langle\cdot, \cdot\rangle$ and they are complex conjugate to each other.
The following lemma is obvious.
Lemma 3.1. The linear generalized complex structures are in 1-1 correspondence with the splittings $\left(V \oplus V^{*}\right) \otimes \mathbb{C}=$ $E_{+} \oplus E_{-}$with $E_{ \pm}$maximal isotropic and $E_{-}=\overline{E_{+}}$.

Now, let $M$ be a manifold and $J$ a bundle endomorphism of $T M \oplus T^{*} M$ such that $J^{2}=-I$, and $J$ is orthogonal with respect to $\langle\cdot, \cdot\rangle$. In the associated eigenbundle decomposition

$$
\left(T_{\mathbb{C}} M \oplus T_{\mathbb{C}}^{*} M\right)=E_{+} \oplus E_{-},
$$

if $\Gamma\left(E_{+}\right)$is closed under the (complexified) Courant bracket, then $E_{+}$is a (complex) Dirac structure on $M$ and one says that $J$ is a generalized complex structure $[10,13]$. In this case, $E_{-}$must also be a Dirac structure since $E_{-}=\overline{E_{+}}$. Indeed ( $E_{+}, E_{-}$) is a complex Lie bialgebroid in the sense of [20], in which $E_{+}$and $E_{-}$are complex conjugate to each other.

The following proposition gives two equivalent definitions of a generalized complex structure.

## Proposition 3.2. A generalized complex structure is equivalent to any of the following:

(1) A bundle endomorphism $J$ of $T M \oplus T^{*} M$ such that $J$ is orthogonal with respect to $\langle\cdot, \cdot\rangle$ and $J^{2}=-I$ satisfying

$$
\begin{equation*}
\left[J e_{1}, J e_{2}\right]-\left[e_{1}, e_{2}\right]-J\left(\left[J e_{1}, e_{2}\right]+\left[e_{1}, J e_{2}\right]\right)=0, \quad \forall e_{1}, e_{2} \in \Gamma\left(T M \oplus T^{*} M\right) \tag{2}
\end{equation*}
$$

(2) A complex Lie bialgebroid ( $E_{+}, E_{-}$) such that its double is the standard Courant algebroid $T_{\mathbb{C}} M \oplus T_{\mathbb{C}}^{*} M$, and $E_{+}$and $E_{-}$are complex conjugate to each other.
Proof. (1) $\Longrightarrow$ (2) As above, $E_{ \pm}$are the ( $\pm \mathbf{i}$ )-eigenbundles of $J$. Since Eq. (2) exactly means that

$$
\left[e_{1} \mp \mathbf{i} J e_{1}, e_{2} \mp \mathbf{i} J e_{2}\right] \in \Gamma\left(E_{ \pm}\right), \quad \forall e_{1}, e_{2} \in \Gamma\left(T M \oplus T^{*} M\right)
$$

it is equivalent to the involutivity of $\Gamma\left(E_{ \pm}\right)$.
(2) $\Longrightarrow$ (1) Define $J: T_{\mathbb{C}} M \oplus T_{\mathbb{C}}^{*} M \rightarrow T_{\mathbb{C}} M \oplus T_{\mathbb{C}}^{*} M$ by setting $\left.J\right|_{E_{+}}=\mathbf{i} I$ and $\left.J\right|_{E_{-}}=-\mathbf{i} I$. Since $E_{+}$and $E_{-}$are complex conjugate to each other, we have $J \bar{e}=\overline{J e}, \forall e \in T_{\mathbb{C}} M \oplus T_{\mathbb{C}}^{*} M$. Therefore $J$ must be the $\mathbb{C}$-linear extension of an endomorphism of $T M \oplus T^{*} M$. It is easy to check that $J$ does indeed satisfy all the axioms as in (1).

The following are two standard examples $[10,13]$.
Examples 3.3. (1) Let $j$ be an almost complex structure on $M$. Then

$$
J=\left(\begin{array}{cc}
j & 0 \\
0 & -j^{*}
\end{array}\right)
$$

is $\langle\cdot, \cdot\rangle$-orthogonal and satisfies $J^{2}=-I . J$ is a generalized complex structure if and only if $j$ is integrable.
(2) Let $\omega$ be a non-degenerate 2 -form on $M$. Then

$$
J=\left(\begin{array}{cc}
0 & -\omega_{b}^{-1} \\
\omega_{b} & 0
\end{array}\right)
$$

where $\omega_{b}: T M \rightarrow T^{*} M$ is the bundle map $\left.X \mapsto X\right\lrcorner \omega$, is a generalized complex structure if and only if $\mathrm{d} \omega=0$, i.e., $\omega$ is a symplectic 2 -form.

## 4. Reduction using Dirac structures

Let $M$ be a manifold, $J$ a generalized complex structure on $M$ and $\varphi$ an action of a Lie group $G$ on $M$ preserving the generalized complex structure $J$. In other words, we have a group homomorphism $\varphi: G \rightarrow \operatorname{Diffeo}(M): g \mapsto \varphi_{g}$ such that, $\forall g \in G$, the bundle endomorphism

(defining the induced $G$-action $\phi$ on $T M \oplus T^{*} M$ ) commutes with $J$, where $\phi_{g}=\varphi_{g *} \oplus \varphi_{g_{-1}}^{*}$. As in Section 3, by $E_{ \pm}$ we denote the $( \pm \mathbf{i}$-eigenbundles of $J$.

Let $M_{0}$ be a $G$-invariant submanifold of $M$ with a free and proper $G$-action so that the quotient space $M_{G}:=M_{0} / G$ is a smooth manifold. Thus one has the following maps:

$$
M \stackrel{i}{\hookleftarrow} M_{0} \stackrel{\pi}{\rightarrow} M_{G} .
$$

The main question that we investigate in this section is: under what condition does $M_{G}$ inherit a generalized complex structure?

Since $\pi$ is surjective and $J$ is $G$-invariant, $E_{ \pm}^{\prime}:=\mathcal{F} \pi\left(\mathcal{B} i\left(E_{ \pm}\right)\right)$are well-defined, complex conjugate pointwise Dirac structures on $M_{G}$. It is simple to check that

$$
E_{ \pm}^{\prime}=\left\{\pi_{*} X+\xi^{\prime} \mid X \in T_{\mathbb{C}} M_{0}, \xi^{\prime} \in T_{\mathbb{C}}^{*} M_{G} \text { and } \exists \xi \in T_{\mathbb{C}}^{*} M \text { st } i_{*} X+\xi \in E_{ \pm} \text {and } \pi^{*} \xi^{\prime}=i^{*} \xi\right\} .
$$

One possible way to ensure that $E_{ \pm}^{\prime}$ are Dirac structures is to use Proposition 2.3 by considering the pull back Dirac structure $\mathcal{B} i\left(E_{ \pm}\right)$and then the push forward structure $\mathcal{F} \boldsymbol{\pi}\left(\mathcal{B} i\left(E_{ \pm}\right)\right)$. Below, however, we will combine these two steps together, which enables us to obtain a stronger result.

In what follows, the foliation of $M_{0}$ defined by the $G$-orbits will be denoted by $\mathcal{F}$, and $(T \mathcal{F})^{0}$ and $\left(T M_{0}\right)^{0}$ will denote the annihilators of $T \mathcal{F}$ and $T M_{0}$ in $T M$ along the submanifold $M_{0}$ respectively.

It is clear that any element $i_{*} X_{m}+\xi_{i(m)} \in T M_{0} \oplus(T \mathcal{F})^{0}$ induces an element $\pi_{*} X_{m}+\xi_{\pi(m)}^{\prime} \in T M_{G} \oplus T^{*} M_{G}$ where $\xi_{\pi(m)}^{\prime}$ is defined by $i^{*} \xi_{\pi(m)}=\pi^{*} \xi_{\pi(m)}^{\prime}$. Indeed, one has a bundle map


The element $i_{*} X_{m}+\xi_{i(m)} \in T M_{0} \oplus(T \mathcal{F})^{0}$ is called a lift of $\pi_{*} X_{m}+\xi_{\pi(m)}^{\prime} \in T M_{G} \oplus T^{*} M_{G}$. Note that, for a given element $v_{n} \in T M_{G} \oplus T^{*} M_{G}$, there exist many different lifts. Indeed, there is a choice of point $m$ in the fiber $\pi^{-1}(n) \subset M_{0}$ involved and $\Pi$ has $T \mathcal{F} \oplus\left(T M_{0}\right)^{0}$ as non-trivial kernel.

Proposition 4.1. The following assertions are equivalent.
(1) $E_{+}^{\prime} \cap E_{-}^{\prime}=0$.
(2) $\left(E_{+}+T_{\mathbb{C}} \mathcal{F}\right) \cap\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right) \cap\left(E_{-}+\left(T_{\mathbb{C}} M_{0}\right)^{0}\right) \subset T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$.
(3) If $z \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$ with $z=z_{+}+z_{-}$such that $z_{ \pm} \in E_{ \pm}$and $z_{ \pm} \in T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}$, then $z_{ \pm} \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$.
(4) $J\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right) \cap\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \subset T \mathcal{F} \oplus\left(T M_{0}\right)^{0}$.
(5) $J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \subset\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)+J\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right)$.
(6) $T M_{0} \oplus(T \mathcal{F})^{0}=\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)+\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right)$.
(7) $T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}=E_{+}^{\prime}+E_{-}^{\prime}$ 。

Proof. (1) $\Leftrightarrow(2)$ Note that

$$
\begin{aligned}
E_{+}^{\prime} \cap E_{-}^{\prime}= & \left\{X^{\prime}+\xi^{\prime} \in T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G} \mid \exists X_{ \pm} \in T_{\mathbb{C}} M_{0} \text { and } \xi_{ \pm} \in T_{\mathbb{C}}^{*} M_{\mid M_{0}}\right. \\
& \text { such that } \left.i_{*} X_{ \pm}+\xi_{ \pm} \in E_{ \pm}, \pi_{*} X_{ \pm}=X^{\prime} \text { and } i^{*} \xi_{ \pm}=\pi^{*} \xi^{\prime}\right\} .
\end{aligned}
$$

Thus, in particular, we have

$$
\begin{aligned}
& X_{ \pm} \in T_{\mathbb{C}} M_{0} \quad \xi_{ \pm} \in\left(T_{\mathbb{C}} \mathcal{F}\right)^{0} \\
& X_{-}-X_{+} \in T_{\mathbb{C}} \mathcal{F} \quad \xi_{-}-\xi_{+} \in\left(T_{\mathbb{C}} M_{0}\right)^{0}
\end{aligned}
$$

Assume that there exists an element $X^{\prime}+\xi^{\prime} \neq 0$ in $E_{+}^{\prime} \cap E_{-}^{\prime}$. Then there exist $i_{*} X_{ \pm}+\xi_{ \pm} \in E_{ \pm}$with $X_{ \pm} \in T_{\mathbb{C}} M_{0}$ and $\xi_{ \pm} \in T_{\mathbb{C}}^{*} M_{\mid M_{0}}$ as above. In particular,

$$
i_{*} X_{-}+\xi_{+} \in\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right)
$$

Since $T_{\mathbb{C}} \mathcal{F} \subset T_{\mathbb{C}} M_{0}$, we get

$$
i_{*} X_{-}+\xi_{+}=\left(i_{*} X_{+}+\xi_{+}\right)+i_{*}\left(X_{-}-X_{+}\right) \in E_{+}+T_{\mathbb{C}} \mathcal{F}
$$

On the other hand, we have

$$
i_{*} X_{-}+\xi_{+}=\left(i_{*} X_{-}+\xi_{-}\right)+\left(\xi_{+}-\xi_{-}\right) \in E_{-}+\left(T_{\mathbb{C}} M_{0}\right)^{0}
$$

Hence

$$
i_{*} X_{-}+\xi_{+} \in\left(E_{+}+T_{\mathbb{C}} \mathcal{F}\right) \cap\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right) \cap\left(E_{-}+\left(T_{\mathbb{C}} M_{0}\right)^{0}\right)
$$

Now $X^{\prime}+\xi^{\prime} \neq 0$ implies that $i_{*} X_{-}+\xi_{+}$must not belong to $T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$. Thus, we have proved that $E_{+}^{\prime} \cap E_{-}^{\prime} \neq 0$ implies

$$
\left(E_{+}+T_{\mathbb{C}} \mathcal{F}\right) \cap\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right) \cap\left(E_{-}+\left(T_{\mathbb{C}} M_{0}\right)^{0}\right) \nsubseteq T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}
$$

It is an easy matter to show that the converse is also true.
(2) $\Rightarrow$ (3) Take $\hat{A}+f \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$ and assume that $\hat{A}+f=z_{+}+z_{-}$with $z_{ \pm} \in E_{ \pm}$and $z_{ \pm} \in$ $T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}$. Then $z_{+}-\hat{A}=-z_{-}+f$ is an element of the triple intersection of the LHS of (2). Hence $z_{ \pm} \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$.
(3) $\Rightarrow$ (2) Any element $z$ in the triple intersection can be written both as $v+\hat{A}$ and as $w+f$ for some $v \in E_{+}$, $\hat{A} \in T_{\mathbb{C}} \mathcal{F}, w \in E_{-}$and $f \in\left(T_{\mathbb{C}} M_{0}\right)^{0}$. We have $w-v=\hat{A}-f \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$. The assumption (3) implies that $v, w \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$. And, finally, $z=v+\hat{A} \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$.
(3) $\Leftrightarrow$ (4) Since $T_{\mathbb{C}} M=E_{+} \oplus E_{-}$, the only solution to $z=z_{+}+z_{-}$, where $z \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$ and $z_{ \pm} \in E_{ \pm}$, is $z_{ \pm}=\frac{1}{2}(z \mp \mathbf{i} J z)$. Since $T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0} \subset T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}$, one has $z_{ \pm} \in T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}$ if and only if $J z \in T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}$. Thus condition (3) can be rewritten as

$$
\left.\begin{array}{c}
z \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0} \\
J z \in T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}
\end{array}\right\} \Longrightarrow J z \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}
$$

which is equivalent to (4).
(4) $\Leftrightarrow$ (5) Dualizing one condition by taking the annihilator with respect to $\langle\cdot, \cdot\rangle$ and applying $J$ to both sides yields the other one.
(5) $\Leftrightarrow$ (6) Since $J^{2}=-I$, (5) is equivalent to

$$
T M_{0} \oplus(T \mathcal{F})^{0} \subset J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)+\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right)
$$

Remembering that $T \mathcal{F} \oplus\left(T M_{0}\right)^{0} \subset T M_{0} \oplus(T \mathcal{F})^{0}$, the equivalence with (6) is obvious.
(6) $\Rightarrow$ (7) Any element $v \in T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}$ has a lift $\tilde{v} \in T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}$. By (6), there exists $k \in T_{\mathbb{C}} \mathcal{F} \oplus\left(T_{\mathbb{C}} M_{0}\right)^{0}$ such that $\tilde{v}-k \in\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right) \cap J\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right)$. Then the vectors $\frac{1}{2}(I-\mathbf{i} J)(\tilde{v}-k)$ and $\frac{1}{2}(I+\mathbf{i} J)(\tilde{v}-k)$ belong to $E_{+} \cap\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right)$ and $E_{-} \cap\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right)$ respectively and are thus the lifts of a pair of vectors $v_{+} \in E_{+}^{\prime}$ and $v_{-} \in E_{-}^{\prime}$ such that $v=v_{+}+v_{-}$.
(7) $\Rightarrow$ (6) Let $\hat{v}$ be a vector of $T M_{0} \oplus(T \mathcal{F})^{0}$. It is a lift of some vector $v \in T M_{G} \oplus T^{*} M_{G}$. Hence $v$ can be written as a sum $v=v_{+}+v_{-}$, where $v_{+} \in E_{+}^{\prime}$ and $v_{-} \in E_{-}^{\prime}$. Choose lifts $\tilde{v}_{+} \in E_{+} \cap\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right)$ and $\tilde{v}_{-} \in E_{-} \cap\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right)$ of $v_{+}$and $v_{-}$respectively. Then $\tilde{v}_{+}+\tilde{v}_{-}$is a lift of $v$ and belongs to $\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right) \cap J\left(T_{\mathbb{C}} M_{0} \oplus\left(T_{\mathbb{C}} \mathcal{F}\right)^{0}\right)$. And $\tilde{v}=\operatorname{Re}\left(\tilde{v}_{+}+\tilde{v}_{-}\right)$is still a lift of $v$ since $v$ is a real vector. Moreover $\tilde{v} \in\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)$. Let $k=\hat{v}-\tilde{v}$. Then it follows that $k \in T \mathcal{F} \oplus\left(T M_{0}\right)^{0}$ since both $\hat{v}$ and $\tilde{v}$ are lifts of $v$.

As an immediate consequence, we have
Corollary 4.2. The direct sum decomposition $T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}=E_{+}^{\prime} \oplus E_{-}^{\prime}$ holds if and only if any element of $T M_{G} \oplus T^{*} M_{G}$ has a lift in $\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)$.

Proof. By Proposition 4.1, the direct sum decomposition holds if and only if

$$
T M_{0} \oplus(T \mathcal{F})^{0}=\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)+\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right) .
$$

The result thus follows from the fact that $\operatorname{ker} \Pi=T \mathcal{F} \oplus\left(T M_{0}\right)^{0}$ and the surjectivity of $\Pi$, where $\Pi$ is the map as in Eq. (3).

It is clear that any $G$-invariant (local) section $\tilde{\sigma}$ of $T M_{0} \oplus(T \mathcal{F})^{0} \rightarrow M_{0}$ induces a (local) section $\sigma$ of $T M_{G} \oplus T^{*} M_{G} \rightarrow M_{G}$. Here, $G$-invariant local sections must be understood in the following obvious sense: $\tilde{\sigma}\left(m_{1}\right)=\phi_{g} \cdot \tilde{\sigma}\left(m_{2}\right)$, for all $m_{1}, m_{2} \in U$ such that $m_{1}=g \cdot m_{2}$ for some $g \in G$. Hence, the bundle map (3) induces a map

$$
\Gamma_{\mathrm{loc}}\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)^{G} \longrightarrow \Gamma_{\mathrm{loc}}\left(T M_{G} \oplus T^{*} M_{G}\right)
$$

Definition 4.3. Let $U$ be an open neighborhood in $M$. A local section $\tilde{\sigma} \in \Gamma\left(\left(T M \oplus T^{*} M\right)_{\mid U}\right)^{G}$ is said to be a lift of a local section $\sigma \in \Gamma\left(\left(T M_{G} \oplus T^{*} M_{G}\right)_{\mid \pi\left(U \cap M_{0}\right)}\right)$ if $\tilde{\sigma}_{\mid U \cap M_{0}} \in \Gamma\left(\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)_{\mid U \cap M_{0}}\right)$ and the diagram

commutes.
Lemma 4.4. Given any local sections $\sigma_{1}, \sigma_{2} \in \Gamma_{\mathrm{loc}}\left(T M_{G} \oplus T^{*} M_{G}\right)$, assume that $\tilde{\sigma}_{1}, \tilde{\sigma}_{2} \in \Gamma_{\mathrm{loc}}\left(T M \oplus T^{*} M\right)^{G}$ are any of their lifts. Then
(1) $\left[\tilde{\sigma}_{1}, \tilde{\sigma}_{2}\right] \in \Gamma_{\mathrm{loc}}\left(T M \oplus T^{*} M\right)^{G}$,
(2) $\left[\tilde{\sigma}_{1}, \tilde{\sigma}_{2}\right]_{\mid M_{0}} \in \Gamma_{\text {loc }}\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)^{G}$,
(3) $\Pi \circ\left[\tilde{\sigma}_{1}, \tilde{\sigma}_{2}\right]_{M_{0}}=\left[\sigma_{1}, \sigma_{2}\right] \circ \pi$,
where the Courant brackets are taken in $\Gamma_{\mathrm{loc}}\left(T M \oplus T^{*} M\right)$ and $\Gamma_{\mathrm{loc}}\left(T M_{G} \oplus T^{*} M_{G}\right)$ as is appropriate. In other words, $\left[\tilde{\sigma}_{1}, \tilde{\sigma}_{2}\right]$ is a lift of $\left[\sigma_{1}, \sigma_{2}\right]$.

Proof. (1) Assume that $\tilde{\sigma}_{1}=X+\xi$ and $\tilde{\sigma}_{2}=Y+\eta$, where $X, Y \in \mathfrak{X}_{\mathrm{loc}}(M)^{G}$ and $\xi, \eta \in \Omega_{\mathrm{loc}}^{1}(M)^{G}$. Then

$$
\left[\tilde{\sigma}_{1}, \tilde{\sigma}_{2}\right]=[X, Y]+\mathcal{L}_{X} \eta-\mathcal{L}_{Y} \xi+\frac{1}{2} d(\xi(Y)-\eta(X))
$$

is clearly $G$-invariant.
(2) First $[X, Y]_{\mid M_{0}} \in \mathfrak{X}\left(M_{0}\right)$ since $X$ and $Y$ belong to $\mathfrak{X}\left(M_{0}\right)$. Now,

$$
\left(\mathcal{L}_{X} \eta\right)(\hat{A})_{\mid M_{0}}=X(\eta(\hat{A}))_{\mid M_{0}}-\eta([X, \hat{A}])_{\mid M_{0}}, \quad \forall A \in \mathfrak{g} .
$$

Since $\eta(\hat{A})_{\mid M_{0}}=0$ and $X$ is tangent to $M_{0}$, we have $X(\eta(\hat{A}))_{\mid M_{0}}=0$. Moreover, $[X, \hat{A}]=0$ because $X$ is $G$-invariant. Hence $\left(\mathcal{L}_{X} \eta\right)(\hat{A})_{\mid M_{0}}=0$. In other words, $\mathcal{L}_{X} \eta_{\mid M_{0}} \in(T \mathcal{F})^{0}$. Similarly, $\mathcal{L}_{Y} \xi_{\mid M_{0}} \in(T \mathcal{F})^{0}$. Finally, $\mathrm{d}(\xi(Y)-\eta(X)) \in(T \mathcal{F})^{0}$. For $\xi(Y)-\eta(X)$ is a $G$-invariant function. Therefore we have $\left[\tilde{\sigma}_{1}, \tilde{\sigma}_{2}\right]_{\mid M_{0}} \in$ $\Gamma_{\text {loc }}\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)^{G}$.
(3) By $\hat{\sigma}_{1}, \hat{\sigma}_{2}$, we denote the sections of $\Gamma_{\text {loc }}\left(T M_{0} \oplus T^{*} M_{0}\right)$ obtained by considering the cotangent parts of $\tilde{\sigma}_{1}$ and $\tilde{\sigma}_{2}$ as elements in $T^{*} M_{0}$. It is clear that $\tilde{\sigma}_{i} \stackrel{i}{\rightsquigarrow} \hat{\sigma}_{i}$ and $\hat{\sigma}_{i} \underset{\rightsquigarrow}{\pi} \sigma_{i}$. The conclusion follows from Lemma 2.2.

Proposition 4.5. Assume that, given any element $v_{n} \in T M_{G} \oplus T^{*} M_{G}$, there exists a local smooth section $\zeta$ of $\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \rightarrow M_{0}$ around some point $m \in \pi^{-1}(n)$ such that $\left.\zeta\right|_{m}$ is a lift of $v_{n}$. Then the following assertions hold:
(1) The subbundles $E_{ \pm}^{\prime} \subset T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}$ are smooth.
(2) Any smooth (global) section of $\Gamma\left(E_{ \pm}^{\prime}\right)$ locally admits a lift to a local section in $\Gamma\left(E_{ \pm}\right)^{G}$.

Proof. (1) Since $E_{ \pm}^{\prime}$ has constant rank, it suffices to prove that any element $v_{n} \in E_{ \pm}^{\prime}$ admits a smooth local section passing through it. Let $\zeta$ be a local section of $\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)$ defined in an open neighborhood $V$ containing $m$ with $\pi(m)=n$ such that $\left.\zeta\right|_{m}$ is a lift of $v_{n}$. Shrinking $V$ if necessary, we can extend $\zeta$ to a local section of $T M \oplus T^{*} M \rightarrow M$, denoted by the same symbol $\zeta$, and defined in an open neighborhood $U$ of $M_{0}$ such that $U \cap M_{0}=V$. Now take a slice $L$ in $U$ through the point $m$ and transversal to the $G$-orbits. Such a slice always exists if $U$ is taken small enough. Let $\tilde{\sigma}$ be the unique $G$-invariant section of $\Gamma\left(\left(T M \oplus T^{*} M\right)_{\mid U}\right)$ such that $\tilde{\sigma}_{\mid L}=\zeta_{\mid L}$. Set $\tilde{\tau}=\frac{1}{2}(I \mp \mathbf{i} J) \circ \tilde{\sigma}$. It is clear that $\tilde{\tau} \in \Gamma\left(E_{ \pm \mid U}\right)$ is a local $G$-invariant smooth section such that $\tilde{\tau}_{\mid U \cap M_{0}} \in \Gamma_{\text {loc }}\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)^{G}$. Therefore, it induces a smooth section $\tau \in \Gamma\left(E_{ \pm \mid \pi(U)}^{\prime}\right)$ through the element $v_{n}$.
(2) Let $v \in \Gamma\left(E_{+}^{\prime}\right)$ be any smooth section around the point $n \in M_{G}$. Choose a basis $\left\{v_{n}^{i}\right\}_{i=1, \ldots, k}$ of $E_{+\mid n}^{\prime}$. Let $\tau^{i}$ be the local smooth section of $E_{+}^{\prime}$ through the element $v_{n}^{i}$ constructed as in (1). Then $\left\{\left.\tau^{i}\right|_{n^{\prime}}\right\}_{i=1, \ldots, k}$ is a basis of $E_{+\mid n^{\prime}}^{\prime}$ when $n^{\prime}$ is in a sufficiently small neighborhood $V$ around $n$. Thus $v=\sum f_{i} \tau^{i}$ for some $f_{i} \in C^{\infty}(V)$. Let $\tilde{\tau}^{i} \in \Gamma\left(\left.E_{ \pm}\right|_{U}\right)$ be the lift of $\tau^{i}$ as in (1) defined on an open neighborhood $U$ such that $U \cap M_{0}=\pi^{-1}(V)$. Choose $\tilde{f}_{i} \in C^{\infty}(U)^{G}$ such that $\tilde{f}_{i \mid M_{0} \cap U}=\pi^{*} f_{i}$. Such $\tilde{f}_{i}$ always exist if $U$ is chosen sufficiently small. Then $\tilde{v}=\sum \tilde{f}_{i} \tilde{\tau}^{i}$ is a lift of $v$ in $\Gamma\left(E_{ \pm}\right)^{G}$.
We are now ready to state the main theorem of this paper.
Theorem 4.6. Let $M$ be a manifold endowed with an action of a Lie group G. Let J be a G-invariant generalized complex structure on $M$. And let $M_{0}$ be a G-invariant submanifold of $M$ where the $G$-action is free and proper so that the quotient $M_{G}=M_{0} / G$ is a manifold. Assume that, given any element $v_{n} \in T M_{G} \oplus T^{*} M_{G}$, there exists a local smooth section $\zeta$ of $\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \rightarrow M_{0}$ around some point $m \in \pi^{-1}(n)$ such that $\left.\zeta\right|_{m}$ is a lift of $v_{n}$. Then there is an induced generalized complex structure $J_{G}$ on $M_{G}$.
Proof. This follows from Corollary 4.2, Proposition 4.5 and Lemma 4.4.
Lemma 4.7. The hypothesis of Proposition 4.5 is satisfied when

$$
\begin{equation*}
\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \text { is a generalized smooth subbundle } \tag{5}
\end{equation*}
$$

and

$$
\begin{equation*}
J\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right) \cap\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \subset T \mathcal{F} \oplus\left(T M_{0}\right)^{0} \tag{6}
\end{equation*}
$$

Proof. For any vector $v_{n} \in T M_{G} \oplus T^{*} M_{G}$, according to Proposition 4.1 and Corollary 4.2, Eq. (6) implies the existence of a lift $\zeta_{m}$ of $v_{n}$ in $\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)$. Since $\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \rightarrow M_{0}$ is a generalized smooth subbundle, it admits a local section $\zeta$ around $m$ in $M_{0}$ which extends $\zeta_{m}$.

Theorem 4.8. Let $M$ be a manifold endowed with an action of a Lie group $G$, and $J$ a $G$-invariant generalized complex structure on $M$. Assume that $M_{0}$ is a $G$-invariant submanifold of $M$ where the $G$-action is free and proper so that the quotient $M_{G}=M_{0} / G$ is a manifold. Then there is an induced generalized complex structure on $M_{G}$ if the hypotheses (5) and (6) of Lemma 4.7 are satisfied.

Theorem 4.8 has several important consequences.
Corollary 4.9. Under the same hypothesis as in Theorem 4.8, if moreover

$$
\begin{equation*}
J\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right)=T \mathcal{F} \oplus\left(T M_{0}\right)^{0} \tag{7}
\end{equation*}
$$

then $M_{G}$ admits an inherited generalized complex structure.
Proof. Since $J$ is orthogonal and $T M_{0} \oplus(T \mathcal{F})^{0}=\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right)^{\perp}\langle\cdot \cdot\rangle$, Eq. (7) implies that $J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)=$ $T M_{0} \oplus(T \mathcal{F})^{0}$. Hence $\left(T M_{0} \oplus(T \mathcal{F})^{0} \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)\right)=T M_{0} \oplus(T \mathcal{F})^{0}$ is smooth. And Eq. (6) is satisfied since $T \mathcal{F} \oplus\left(T M_{0}\right)^{0} \subset T M_{0} \oplus(T \mathcal{F})^{0}$. The result follows from Theorem 4.8.

Remark 4.10. This is exactly what happens in the case of Marsden-Weinstein reduction [23]. In this case, $J=$ $\left(\begin{array}{cc}0 & -\omega_{b}^{-1} \\ \omega_{b} & 0\end{array}\right)$, and $M_{0}=\mu^{-1}(0)$, where $\omega \in \Omega^{2}(M)$ is a symplectic form and $\mu: M \rightarrow \mathfrak{g}^{*}$ is an equivariant momentum map: $\hat{A}\lrcorner \omega=d\langle\mu, A\rangle, \forall A \in \mathfrak{g}$. One checks easily that $J(T \mathcal{F})=\left(T M_{0}\right)^{0}$, and therefore $J\left(T M_{0}\right)^{0}=T \mathcal{F}$ since $J^{2}=-I$. Hence the conditions in Corollary 4.9 are satisfied.

More generally one sees that these conditions hold when $J$ is a symplectic structure twisted by a $B$-field.
Corollary 4.11. Let $(M, \omega)$ be a symplectic manifold endowed with an action of a Lie group $G$ preserving the symplectic structure. Assume that there exists a $G$-invariant closed 2-form $B$ on $M$ and an equivariant momentum map $\mu: M \rightarrow \mathfrak{g}^{*}$.

$$
\begin{equation*}
\hat{A}\lrcorner \omega=d\langle\mu, A\rangle, \quad \forall A \in \mathfrak{g} \tag{8}
\end{equation*}
$$

Assume that 0 is a regular value of $\mu$ and the $G$-action is free and proper. Thus $M_{0}=\mu^{-1}(0)$ is a G-invariant submanifold of $M$ and the quotient $M_{G}=M_{0} / G$ is a smooth manifold. If $i^{*} B$, where $i: M_{0} \rightarrow M$ is the inclusion, is basic with respect to the G-action, then the generalized complex structure

$$
J=\left(\begin{array}{cc}
1 & 0 \\
B_{b} & 1
\end{array}\right)\left(\begin{array}{cc}
0 & -\omega_{b}^{-1} \\
\omega_{b} & 0
\end{array}\right)\left(\begin{array}{cc}
1 & 0 \\
-B_{b} & 1
\end{array}\right)
$$

on $M$ induces a generalized complex structure on $M_{G}$.
Proof. Note that the assumption $i^{*} B$ being basic implies that $T M_{0} \oplus(T \mathcal{F})^{0}$ is stable under the bundle map $\left(\begin{array}{cc}1 & 0 \\ \pm B_{D} & 1\end{array}\right)$ of $T M \oplus T M^{*}$. By the discussion in Remark 4.10, we know that $T M_{0} \oplus(T \mathcal{F})^{0}$ is also stable under $\left(\begin{array}{cc}0 & -\omega_{b}^{-1} \\ \omega_{b} & 0\end{array}\right)$. The conclusion thus follows from Corollary 4.9.

Here is yet another important situation.
Corollary 4.12. Under the same hypothesis as in Theorem 4.8, if moreover

$$
\begin{equation*}
J\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right) \cap\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)=0 \tag{9}
\end{equation*}
$$

then $M_{G}$ admits an inherited generalized complex structure.
In particular, if $J=\left(\begin{array}{cc}j & 0 \\ 0 & -j^{*}\end{array}\right)$ is a usual complex structure, the above relation is nothing else than the Guillemin-Sternberg condition [11]:

$$
\begin{equation*}
T M=T M_{0} \oplus j(T \mathcal{F}) \tag{10}
\end{equation*}
$$

In this case, the induced generalized complex structure is still a complex structure.
Proof. Since Eq. (9) implies Eq. (6), Condition (5) of Proposition 4.1 holds. Together with Eq. (9), this implies that

$$
J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \subset\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \oplus J\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right)
$$

Since $T \mathcal{F} \oplus\left(T M_{0}\right)^{0} \subset T M_{0} \oplus(T \mathcal{F})^{0}$, the projection of $J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)$ onto $T M_{0} \oplus(T \mathcal{F})^{0}$ parallel to $J\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right)$ is equal to $\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)$. Therefore, we have

$$
J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)=\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \oplus J\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{0}\right)
$$

which implies that $\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus(T \mathcal{F})^{0}\right)$ must be a smooth subbundle. Thus the conclusion follows from Theorem 4.8.

The second part of Corollary 4.12 can be easily checked and is left for the reader.
Corollary 4.13. Under the same hypothesis as in Theorem 4.8, if moreover there exists a Riemann metric $g$ such that $\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{\perp} \oplus\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{0}$ is $J$-stable, then $M_{G}$ admits an inherited generalized complex structure. Here $\perp$ refers to the orthogonal subspace in $T M$ with respect to the metric $g$.

In particular, if $(M, g, j)$ is a $G$-invariant Hermitian manifold such that $T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}$ is $j$-stable, then $M_{G}$ admits an inherited complex structure.

Proof. Since $L:=\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{\perp} \oplus\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{0}$ is $J$-stable, one has $L \subset\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \cap J\left(T M_{0} \oplus\right.$ $\left.(T \mathcal{F})^{0}\right)$. Let $Q$ be the projection of $\left(T M \oplus T^{*} M\right)_{\mid M_{0}}$ onto $(T \mathcal{F})^{\perp} \oplus\left(\left(T M_{0}\right)^{\perp}\right)^{0}$ parallel to $T \mathcal{F} \oplus\left(T M_{0}\right)^{0}$. Then, since $T \mathcal{F} \oplus\left(T M_{0}\right)^{0} \subset T M_{0} \oplus(T \mathcal{F})^{0}$, one has

$$
Q\left(T M_{0} \oplus(T \mathcal{F})^{0}\right) \subset\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{\perp} \oplus\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{0}=L
$$

Now fix an element $v$ of $T M_{G} \oplus T^{*} M_{G}$, and let $\tilde{v} \in T M_{0} \oplus(T \mathcal{F})^{0}$ be a lift of $v$. Then $Q(\tilde{v})$ is a lift of $v$ in $L$. The bundle $L$ being smooth, there exists a section $s$ of $L$ extending $Q(\tilde{v})$. Hence the hypothesis of Proposition 4.5 is satisfied and the result follows from Theorem 4.6.

In particular, if $J=\left(\begin{array}{cc}j_{0}^{j} & { }_{-j^{*}}\end{array}\right)$, where $j$ preserves $T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}$, and $J$ is orthogonal with respect to $g$, then the smooth subbundle $L$ of $T M_{0} \oplus(T \mathcal{F})^{0}$ is indeed $J$-invariant.

Remark 4.14. Note that the induced complex structure on the quotient space in Kähler reduction can be considered as a special case of the above situation.

Corollary 4.15. Let $(M, j)$ be a complex manifold endowed with an action of a Lie group $G$ such that $j$ is $G$ invariant. Let $M_{0}$ be a G-invariant submanifold of $M$, where the $G$-action is free and proper so that the quotient $M_{G}=M_{0} / G$ is a manifold. Assume that, for any $X_{n} \in T_{n} M_{G}, \xi_{n} \in T_{n}^{*} M_{G}$, there exists a point $m \in M_{0}$ with $\pi(m)=n$ and local sections $\tilde{X} \in \Gamma_{\text {loc }}\left(T M_{0} \cap j T M_{0}\right), \tilde{\xi} \in \Gamma_{\mathrm{loc}}\left((T \mathcal{F}+j T \mathcal{F})^{0}\right)$ such that $\pi_{*}\left(\left.\tilde{X}\right|_{m}\right)=X_{n}$ and $\pi^{*} \xi_{n}=\left.\tilde{\xi}\right|_{m}$. Then $M_{G}$ admits an inherited generalized complex structure, which is still a complex structure.

In particular, the above conditions are satisfied if $T M_{0} \cap j T M_{0}$ and $T \mathcal{F}+j T \mathcal{F}$ are generalized smooth subbundles of $T M_{0}$.

Proof. The above hypothesis is the projection of the hypothesis of Proposition 4.5 onto the tangent and cotangent bundles.

## 5. Description of $J_{G}$

This section is devoted to an explicit description of the induced generalized complex structure $J_{G}$ under the assumption that the hypothesis of Theorem 4.6 holds.

Let $B$ denote the vector bundle $T M_{0} \oplus(T \mathcal{F})^{0}$ and $B^{\perp}$ its $\langle\cdot, \cdot\rangle$-orthogonal subbundle: $T \mathcal{F} \oplus\left(T M_{0}\right)^{0}$. As in Corollary 4.2, we know that every vector in $T M_{G} \oplus T^{*} M_{G}$ has a lift in $B \cap J B$. In other words, the restriction of the bundle map $\Pi$ (as in Eq. (3)) to $B \cap J B$ is surjective. Then $\Pi_{\mid B \cap J B}$ induces a $G$-invariant vector bundle map

which is indeed a pullback bundle. Note that $\operatorname{ker}_{\mid B \cap J B}=B^{\perp} \cap J B$. Now, by Corollary 4.2 and Proposition 4.1, we have $J B^{\perp} \cap B \subset B^{\perp}$. Moreover since $B^{\perp} \subset B$, we thus have $J B^{\perp} \cap B \subset B^{\perp} \cap J B$. Since $J^{2}=-I$, it follows that $J B^{\perp} \cap B=B^{\perp} \cap J B$. It is simple to see that $B^{\perp} \cap J B$ is $J$-stable. Therefore, $J_{\mid B \cap J B}$ induces a bundle isomorphism

whose $G$-invariance implies that it factorizes through $\Xi$ so that it induces a bundle map $J_{G}$ as the inherited generalized complex structure


Thus we obtain the following
Theorem 5.1. Under the same hypothesis as for Theorem 4.6, the induced generalized complex structure $J_{G}$ on $M_{G}$ can be described by the following commutative diagram:


Hence, if $\tilde{v} \in B \cap J B$ is a lift of $v \in T M_{G} \oplus T^{*} M_{G}$, then $J \tilde{v} \in B \cap J B$ is a lift of $J_{G} v \in T M_{G} \oplus T^{*} M_{G}$.
Remark 5.2. In [9], Crainic showed that a generalized complex structure $J$ is an endomorphism of the generalized tangent bundle $T M \oplus T^{*} M$ built out of a Poisson bivector $\pi$, an endomorphism $N$ of the tangent bundle and a 2 -form $\sigma$ :

$$
J=\left(\begin{array}{cc}
N & \pi^{\sharp} \\
\sigma_{b} & -N^{*}
\end{array}\right)
$$

with $N^{2}+\pi^{\sharp} \sigma_{\mathrm{b}}=-\mathrm{idn}$, which satisfy some compatibility conditions resembling those given by KosmannSchwarzbach, Magri and Morosi [17,22] in their definition of Poisson Nijenhuis structures (see also [18,28]). It would be interesting to investigate the meaning of each component for the reduction $J_{G}$.

## 6. Reduction of generalized Kähler structures

The generalized Kähler structure as introduced by Hitchin [13] and Gualtieri [10] consists of a pair of commuting generalized complex structures ( $J_{1}, J_{2}$ ) such that $\left\langle J_{1} J_{2} \cdot, \cdot\right\rangle$ is positive definite.

Example 6.1. If $(M, \omega, j)$ is a usual Kähler manifold, then

$$
J_{1}=\left(\begin{array}{cc}
0 & -\omega_{b}^{-1} \\
\omega_{b} & 0
\end{array}\right) \quad J_{2}=\left(\begin{array}{cc}
j & 0 \\
0 & -j^{*}
\end{array}\right)
$$

defines a generalized Kähler structure.
As in Section 4, we assume that $M_{0}$ is a $G$-invariant submanifold of $M$ where the $G$-action is free and proper so that the quotient $M_{G}=M_{0} / G$ is a manifold. Since $T M \oplus T^{*} M$ decomposes as the direct sum of four different subbundles with each being constituted of the common eigenvectors of $J_{1}$ and $J_{2}$ determined by a given pair of eigenvalues, it is natural to ask whether the reduction procedure outlined in Section 4 can be applied to $J_{1}$ and $J_{2}$ simultaneously to get a generalized Kähler structure on the quotient $M_{G}$.

Let us introduce some notation. By $E^{ \pm}$and $E_{ \pm}$we denote the $\pm \mathrm{i}$-eigenbundles of $J_{1}$ and $J_{2}$ respectively. Let $B_{\mathbb{C}}=B \otimes \mathbb{C}$. For any subbundle $V$ of $T_{\mathbb{C}} M \oplus T_{\mathbb{C}}^{*} M, \Phi(V)$ denotes the subbundle $\Pi\left(V \cap B_{\mathbb{C}}\right)$ of $T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}$, where $\Pi$ is the bundle map as in Eq. (3).

Proposition 6.2. Assume that $\left(J_{1}, J_{2}\right)$ is a $G$-invariant Kähler structure.
(1) The following two statements are equivalent:

$$
\begin{equation*}
T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}=\Phi\left(E^{+} \cap E_{+}\right)+\Phi\left(E^{+} \cap E_{-}\right)+\Phi\left(E^{-} \cap E_{+}\right)+\Phi\left(E^{-} \cap E_{-}\right) \tag{11}
\end{equation*}
$$

and

$$
\Pi\left(B \cap J_{1} B \cap J_{2} B\right)=T M_{G} \oplus T^{*} M_{G},
$$

where, as in Section 5, $B=T M_{0} \oplus(T \mathcal{F})^{0}$.
(2) If the above condition is satisfied, then the above sum is direct and

$$
\Phi\left(E^{ \pm} \cap E_{ \pm}\right)=\Phi\left(E^{ \pm}\right) \cap \Phi\left(E_{ \pm}\right)
$$

Proof. (1) $\Rightarrow$ Take $v \in T M_{G} \oplus T^{*} M_{G}$. By assumption, it can be decomposed as

$$
v=\Pi\left(\tilde{v}_{+}^{+}\right)+\Pi\left(\tilde{v}_{-}^{+}\right)+\Pi\left(\tilde{v}_{+}^{-}\right)+\Pi\left(\tilde{v}_{-}^{-}\right),
$$

where $\tilde{v}_{ \pm}^{ \pm} \in E^{ \pm} \cap E_{ \pm} \cap B_{\mathbb{C}}$. Let

$$
\tilde{v}=\tilde{v}_{+}^{+}+\tilde{v}_{-}^{+}+\tilde{v}_{+}^{-}+\tilde{v}_{-}^{-} .
$$

Then $\tilde{v} \in B_{\mathbb{C}}$ and $\Pi(\tilde{v})=v$. Hence $\tilde{v}$ is a lift of $v$. Moreover,

$$
J_{1} \tilde{v}=\mathrm{i}\left(\tilde{v}_{+}^{+}+\tilde{v}_{-}^{+}-\tilde{v}_{+}^{-}-\tilde{v}_{-}^{-}\right) \in B_{\mathbb{C}} \quad \text { and } \quad J_{2} \tilde{v}=\mathrm{i}\left(\tilde{v}_{+}^{+}-\tilde{v}_{-}^{+}+\tilde{v}_{+}^{-}-\tilde{v}_{-}^{-}\right) \in B_{\mathbb{C}} .
$$

Hence, $\tilde{v} \in J_{1} B_{\mathbb{C}}$ and $\tilde{v} \in J_{2} B_{\mathbb{C}}$ since $J_{1}^{2}=J_{2}^{2}=-I$. Therefore $\operatorname{Re}(\tilde{v}) \in B \cap J_{1} B \cap J_{2} B$ is a lift of $v \in T M_{G} \oplus T^{*} M_{G}$.
$\Leftarrow$ Conversely, if any $v \in T M_{G} \oplus T^{*} M_{G}$ has a lift $\tilde{v}$ in $B \cap J_{1} B \cap J_{2} B$, one has

$$
\begin{aligned}
v= & \Pi\left(\frac{1}{2}\left(I-\mathrm{i} J_{1}\right) \frac{1}{2}\left(I-\mathrm{i} J_{2}\right) \tilde{v}\right)+\left(\frac{1}{2}\left(I-\mathrm{i} J_{1}\right) \frac{1}{2}\left(I+\mathrm{i} J_{2}\right) \tilde{v}\right) \\
& +\left(\frac{1}{2}\left(I+\mathrm{i} J_{1}\right) \frac{1}{2}\left(I-\mathrm{i} J_{2}\right) \tilde{v}\right)+\left(\frac{1}{2}\left(I+\mathrm{i} J_{1}\right) \frac{1}{2}\left(I+\mathrm{i} J_{2}\right) \tilde{v}\right) .
\end{aligned}
$$

Eq. (11) thus follows.
(2) Finally, since

$$
\begin{equation*}
\Phi\left(E^{ \pm} \cap E_{ \pm}\right) \subseteq \Phi\left(E^{ \pm}\right) \cap \Phi\left(E_{ \pm}\right) \tag{12}
\end{equation*}
$$

the condition

$$
\begin{equation*}
T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}=\Phi\left(E^{+} \cap E_{+}\right)+\Phi\left(E^{+} \cap E_{-}\right)+\Phi\left(E^{-} \cap E_{+}\right)+\Phi\left(E^{-} \cap E_{-}\right) \tag{13}
\end{equation*}
$$

implies that

$$
\begin{equation*}
T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}=\Phi\left(E^{+}\right) \cap \Phi\left(E_{+}\right)+\Phi\left(E^{+}\right) \cap \Phi\left(E_{-}\right)+\Phi\left(E^{-}\right) \cap \Phi\left(E_{+}\right)+\Phi\left(E^{-}\right) \cap \Phi\left(E_{-}\right) \tag{14}
\end{equation*}
$$

and

$$
T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}=\Phi\left(E^{+}\right)+\Phi\left(E^{-}\right), \quad T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}=\Phi\left(E_{+}\right)+\Phi\left(E_{-}\right)
$$

Applying Proposition 4.1 to $J_{1}$ and $J_{2}$, we obtain

$$
\Phi\left(E^{+}\right) \cap \Phi\left(E^{-}\right)=0 \quad \text { and } \quad \Phi\left(E_{+}\right) \cap \Phi\left(E_{-}\right)=0 .
$$

This implies that the sums in (13) and (14) must be direct. Hence Eq. (12) implies that $\Phi\left(E^{ \pm} \cap E_{ \pm}\right)=$ $\Phi\left(E^{ \pm}\right) \cap \Phi\left(E_{ \pm}\right)$.

Theorem 6.3. Let $\left(M, J_{1}, J_{2}\right)$ be a $G$-invariant generalized Kähler manifold. Assume that $M_{0}$ is a $G$-invariant submanifold of $M$ where the $G$-action is free and proper so that the quotient $M_{G}=M_{0} / G$ is a manifold. If, for any $v_{n} \in T M_{G} \oplus T^{*} M_{G}$, there exists a point $m \in M_{0}$ and a local smooth section $\zeta$ of $B \cap J_{1} B \cap J_{2} B \rightarrow M_{0}$ around $m$ such that $\Pi\left(\left.\zeta\right|_{m}\right)=v_{n}$, then there exists an inherited generalized Kähler structure ( $J_{1 G}, J_{2 G}$ ) on $M_{G}$ such that

$$
\begin{align*}
& \Pi\left(J_{1} w\right)=J_{1 G} \Pi(w)  \tag{15}\\
& \Pi\left(J_{2} w\right)=J_{2 G} \Pi(w)
\end{align*} \quad \forall w \in B \cap J_{1} B \cap J_{2} B .
$$

In particular, this condition holds if

- $B=B \cap J_{1} B \cap J_{2} B+B^{\perp}$ and
- $B \cap J_{1} B \cap J_{2} B$ is a generalized smooth subbundle.

Proof. According to Theorem 4.6, the generalized complex structures $J_{1}$ and $J_{2}$ induce a pair of generalized complex structures $J_{1 G}$ and $J_{2 G}$ on $M_{G}$ satisfying Eq. (15). Let $E^{\prime \pm}$ and $E_{ \pm}^{\prime}$ denote their $\pm \mathbf{i}$-eigenbundles respectively. By Proposition 6.2, we have

$$
T_{\mathbb{C}} M_{G} \oplus T_{\mathbb{C}}^{*} M_{G}=\left(E^{\prime+} \cap E_{+}^{\prime}\right) \oplus\left(E^{\prime+} \cap E_{-}^{\prime}\right) \oplus\left(E^{\prime-} \cap E_{+}^{\prime}\right) \oplus\left(E^{\prime-} \cap E_{-}^{\prime}\right),
$$

which implies that $J_{1 G}$ and $J_{2 G}$ commute.
Finally, for $v \in T M_{G} \oplus T^{*} M_{G}$, choose $w \in B \cap J_{1} B \cap J_{2} B$. By Eq. (15), we have

$$
\left\langle J_{1 G} J_{2 G} v, v\right\rangle=\left\langle J_{1 G} J_{2 G} \Pi(w), \Pi(w)\right\rangle=\left\langle\Pi\left(J_{1} J_{2} w\right), \Pi(w)\right\rangle=\left\langle J_{1} J_{2} w, w\right\rangle,
$$

where the last equality follows from the fact that $\left.\Pi\right|_{B}$ preserves the scalar products. It thus follows that $\left\langle J_{1 G} J_{2 G} \cdot, \cdot\right\rangle$ is positive definite. This concludes the proof.

The following corollary is to Theorem 6.3 what Corollary 4.13 is to Theorem 4.6.
Corollary 6.4. Let $\left(M, J_{1}, J_{2}\right)$ be a G-invariant generalized Kähler manifold. Assume that $M_{0}$ is a $G$-invariant submanifold of $M$, where the $G$-action is free and proper so that the quotient $M_{G}=M_{0} / G$ is a manifold. Assume that there exists a Riemann metric $g$ such that $\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{\perp} \oplus\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{0}$ is stable under both $J_{1}$ and $J_{2}$; then $M_{G}$ admits an inherited generalized complex structure.
Proof. The proof is exactly the same as for Corollary 4.13 except that, here, since $L$ is both $J_{1}$ - and $J_{2}$-invariant, one has $L \subset B \cap J_{1} B \cap J_{2} B$. Then the conclusion follows from Theorem 6.3.

As proved by Gualtieri [10], a generalized Kähler structure ( $J_{1}, J_{2}$ ) on a manifold $M$ is fully characterized by a quadruple ( $g, b, J_{+}, J_{-}$), where $g$ is a Riemannian metric, $b$ is a 2 -form and $J_{ \pm}$are two (integrable) complex structures on $M$, compatible with $g$, such that

$$
\mathrm{d} b(X, Y, Z)=\mathrm{d} \omega_{ \pm}\left(J_{ \pm} X, J_{ \pm} Y, J_{ \pm} Z\right), \quad \forall X, Y, Z \in \mathfrak{X}(M)
$$

with $\omega_{ \pm} \in \Omega^{2}(M)$ defined by $\left\langle\omega_{ \pm} X, Y\right\rangle= \pm g\left(J_{ \pm} X, Y\right)$. These data explicitly determine the pair of generalized complex structures

$$
\begin{aligned}
J_{1} & =\frac{1}{2}\left(\begin{array}{ll}
1 & 0 \\
b & 1
\end{array}\right)\left(\begin{array}{cc}
J_{+}+J_{-} & -\left(\omega_{+}^{-1}+\omega_{-}^{-1}\right) \\
\omega_{+}+\omega_{-} & -\left(J_{+}^{*}+J_{-}^{*}\right)
\end{array}\right)\left(\begin{array}{cc}
1 & 0 \\
-b & 1
\end{array}\right) \\
J_{2} & =\frac{1}{2}\left(\begin{array}{ll}
1 & 0 \\
b & 1
\end{array}\right)\left(\begin{array}{cc}
J_{+}-J_{-} & -\left(\omega_{+}^{-1}-\omega_{+}^{-1}\right) \\
\omega_{+}-\omega_{-} & -\left(J_{+}^{*}-J_{-}^{*}\right)
\end{array}\right)\left(\begin{array}{cc}
1 & 0 \\
-b & 1
\end{array}\right) .
\end{aligned}
$$

Here, for simplicity, we identify a 2 -form with its associated bundle map.
Using exactly this same $g$ and applying Corollary 6.4, we are led to the main result of this section, which generalizes the usual Kähler reduction $[11,12,16]$.

Theorem 6.5. Let $\left(M, J_{1}, J_{2}\right)$ be a $G$-invariant generalized Kähler manifold. Assume that $M_{0}$ is a $G$-invariant submanifold of $M$, where the $G$-action is free and proper so that the quotient $M_{G}=M_{0} / G$ is a manifold. Let $\left(g, b, \omega_{+}, \omega_{-}\right)$be the quadruple associated with a generalized Kähler structure $\left(J_{1}, J_{2}\right)$ as in [10]. If $\omega_{ \pm}(T \mathcal{F})=$ $\left(T M_{0}\right)^{0}$ and $(T \mathcal{F})^{\perp} \cap T M_{0}$ is stable under $\omega_{ \pm}^{-1} b$, then $M_{G}$ inherits a generalized Kähler structure.
Proof. It is sufficient to check that the conditions in Corollary 6.4 are satisfied.
First, since $\omega_{ \pm}$are antisymmetric and non-degenerate, $\omega_{ \pm}(T \mathcal{F})=\left(T M_{0}\right)^{0}$ implies $\omega_{ \pm}\left(T M_{0}\right)=(T \mathcal{F})^{0}$.
Second, $\omega_{ \pm}(T \mathcal{F})=\left(T M_{0}\right)^{0}$ also implies $\omega_{ \pm}\left(T \mathcal{F}^{\perp}\right)=\left(T M_{0}^{\perp}\right)^{0}$ because $J_{ \pm}$are isometric with respect to $g$. Therefore,

$$
\begin{equation*}
\omega_{ \pm}\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{\perp}=\omega_{ \pm}\left(T \mathcal{F}^{\perp} \cap T M_{0}\right)=\left(T M_{0}^{\perp}\right)^{0} \cap(T \mathcal{F})^{0}=\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{0} \tag{16}
\end{equation*}
$$

Finally, one easily checks that the image of any

$$
v+f \in\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{\perp} \oplus\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{0}
$$

under

$$
J_{1} \pm J_{2}=\left(\begin{array}{ll}
1 & 0 \\
b & 1
\end{array}\right)\left(\begin{array}{cc}
J_{ \pm} & -\omega_{ \pm}^{-1} \\
\omega_{ \pm} & -J_{ \pm}^{*}
\end{array}\right)\left(\begin{array}{cc}
1 & 0 \\
-b & 1
\end{array}\right)
$$

lies in $\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{\perp} \oplus\left(T \mathcal{F} \oplus\left(T M_{0}\right)^{\perp}\right)^{0}$ if and only if both Eq. (16) and the condition $\omega_{ \pm}^{-1} b\left((T \mathcal{F})^{\perp} \cap T M_{0}\right) \subset$ $(T \mathcal{F})^{\perp} \cap T M_{0}$ hold.

Note that $\omega_{ \pm}(T \mathcal{F})=\left(T M_{0}\right)^{0}$ is satisfied when $M_{0}$ is the zero level set of an equivariant momentum map. Thus the theorem above reduces to the usual Kähler reduction when $M$ is a Kähler manifold [11,12,16].

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